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| | | | US-PGPUB | 15:43 |
| 58 | 18 | (angular near3 sensor) same (base and | EPO; JPO; | 2003/07/02 |
| | | (cover or housing)) | DERWENT | 15:46 |

fixed onto the holding plate, an elastic body disposed on an end part of at least one selected from the holding plate and circuit board, a case housing the resonator, first base, holding plate, circuit board and elastic body and provided with an opening, and a second base put in place so as to close the opening of the case. The resonator has a short side and a long side. The resonator is located with the direction of the long side thereof arranged perpendicular to the second base, the elastic body is located between an end part of at least one selected from the holding plate and circuit board and the walls of the case, and at least one selected from the holding plate and circuit board is held by the case with an elastic pressure of the elastic body, thereby allowing the compression rate of the elastic body to be prevented from varying. As a result, an angular velocity sensor having stable output characteristics is realized.

CLAIMS:

1. An angular velocity sensor comprising: (a) a resonator including a resonating member and a connecting member; (b) a first base connected to said connecting member; (c) a holding plate to hold said first base; (d) a circuit (39) board fixed onto said holding plate; (e) an elastic body disposed on an end part of at least one selected from said holding plate and circuit board; and (f) a case housing said resonator, first base, holding plate, circuit board and elastic body and having an opening, wherein said elastic body is located between an inner walls of said case an end part of at least one of said holding plate and said circuit board, and at least one selected from said holding plate and circuit board is held by said case via an elastic pressure of said elastic body.

- 2. The angular velocity sensor according to claim 1, further comprising (g) a second base put in place so as to close said opening of said case, wherein said resonator has a short side and a long side, and said resonator is located in such a way as said long side of said resonator is directed perpendicular to said second base.
 - 3. The angular velocity sensor according to claim 2, wherein said resonator comprises a first resonating member, a second resonating member, a driving electrode and a detecting electrode, each respective end part of said first resonating member and second resonating member is connected to said connecting member, and said driving electrode and detecting electrode are disposed on at least one selected from said first resonator and second resonator.
 - 4. The angular velocity sensor according to claim 3, wherein said driving electrode and detecting electrode have an output terminal, respectively, said first base has a plurality of terminal insertion holes, and said respective output terminals pass through said plurality of terminal insertion holes.

- 5. The angular velocity sensor according to claim 3, wherein said circuit board has an electronic device, a power supply electrode, a GND electrode and an output electrode, and said electronic device processes an output signal produced at said detecting electrode according to an angular velocity.
- 6. The angular velocity sensor according to claim 3, wherein said case is shaped like a bottomed cylinder.
- 7. The angular velocity sensor according to claim 1, wherein said elastic body is a rubber molded body formed of rubber.
- 8. The angular velocity sensor according to claim 1, further comprising: (h) a cover that is fixed onto said first base and covers said resonator.
- The angular velocity sensor according to claim 1, further comprising: (g) a second base put in place so as to close said opening of said case; and (h) a cover that is fixed onto said first base and covers said resonator, wherein said resonator has a short side and a long side, said resonator is located in such a way as said long side of said resonator is directed perpendicular to said second base, said resonator comprises a first resonating member, a second resonating member, a driving electrode and a detecting electrode, each respective end part of said first resonating member and second resonating member is connected to said connecting member, said driving electrode and detecting electrode are disposed on at least one selected from said first resonator and second resonator, said driving electrode and detecting electrode have an output terminal, respectively, said first base has a plurality of terminal insertion holes, said respective output terminals pass through said plurality of terminal insertion holes, said circuit board has an electronic device, a power supply electrode, a GND electrode and an output electrode, said electronic device processes an output signal produced at said detecting electrode according to an angular velocity, and said case is shaped like a bottomed cylinder.
- 10. The angular velocity sensor according to claim 9, wherein said holding plate has at least two holding protrusions, said two holding protrusions are fixed onto said circuit board, thereby allowing said circuit board to be held by said holding plate.
- 11. The angular velocity sensor according to claim 9, wherein said elastic body has a small cross-sectional area part, and said small cross-sectional area part reduces a compressive force of said resonator in a direction perpendicular to said long side direction of said resonator.
- 12. The angular velocity sensor according to claim 9, wherein a center of mass formed by combining said resonator, first base, cover, holding plate and circuit board almost coincides with a center of mass of said elastic body.

- 13. The angular velocity sensor according to claim 9, wherein said holding plate has at least two holding members, and said two holding members are swaged onto said first base, thereby allowing said first base to be affixed to said holding plate.
- 14. A manufacturing method of angular velocity sensors comprising the steps of: (a) producing a resonator having a resonating member and a connecting member; (b) producing a first base; (c) producing a holding plate; (d) producing a circuit board; (e) producing an elastic body; (f) producing a case; (g) connecting said connecting member of said resonator to said first base; (h) having said circuit board held onto said first base; (i) fixing said first base onto said holding plate; (j) putting together said resonator, first base, holding plate, circuit board and elastic body so as to have an end part of at least one selected from said holding plate and circuit board held by said elastic body; and (k) having said assembly formed of said resonator, first base, holding plate, circuit board and elastic body housed in said case so as to have said holding plate and circuit board located inside said case via said elastic body.
- 15. The manufacturing method of angular velocity sensors according to claim 14, further comprising the step of: (i) producing a second base, wherein said resonator has a short side and a long side, said step (j) has the step of putting together said resonator, first base, holding plate, circuit board, second base and elastic body so as to have an end part of at least one selected from said holding plate and circuit board held by said elastic body, and said step (k) has the steps of: pressing into a case an assembly formed of said resonator, first base, holding plate, circuit board, second base and elastic body so as to have said long side direction of said resonator arranged perpendicular to said second base; and closing an opening of said case with said second base in such a way as having at least one selected from said holding plate and circuit board held onto said case by an elastic pressure of said elastic body.
- 16. The manufacturing method of angular velocity sensors according to claim 15, wherein said step of producing said resonator has the step of producing a resonator comprising a first resonating member, a second resonating member, a driving electrode and a detecting electrode, each respective end part of said first resonating member and second resonating member is connected to said connecting member, and said driving electrode and detecting electrode are disposed on at least one selected from said first resonating member and second resonating member.
- 17. The manufacturing method of angular velocity sensors according to claim 14, further comprising the step of: (m) producing a cover; wherein said step (j) includes a step of fixing said cover onto said first base so as to cover said resonator.

- 18. The manufacturing method of angular velocity sensors according to claim 14, wherein said driving electrode and detecting electrode have an output terminal, respectively, said first base has a plurality of terminal insertion holes, and said step (i) includes the step of passing said respective output terminals through said plurality of terminal insertion holes.
- 19. The manufacturing method of angular velocity sensors according to claim 14, wherein said circuit board includes an electronic device, a power supply electrode, a GND electrode and an output electrode, and said electronic device processes an output signal produced at said detecting electrode according to an angular velocity.
- 20. The manufacturing method of angular velocity sensors according to claim 15, wherein a small cross-sectional area part is provided to said elastic body in said step of producing said elastic body, said holding plate and circuit board are located inside said case via said small cross-sectional area part of said elastic body, and said small cross-sectional area part allows a compressive force to be reduced in said long side direction of said resonator.
- 21. The manufacturing method of angular velocity sensors according to claim 14, wherein said step of producing said elastic body includes the step of producing a molded rubber piece by applying a molding process to a rubber material.



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Last Name = YAMAZAKI First Name = TOSHIO

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| Application# | Patent# | | | | Inventor Name |
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